

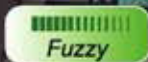


# PID SERIES

## Digital PID Temperature Controllers / Process Controllers

### New Release New LED Module

PAT.NO. : M347604 (Taiwan)  
ZL200820301949.5 (China)



บริษัท ทีพีเทค จำกัด

# BEST CHOICE FOR PROCESS AND TEMPERATURE CONTROL

**Application: Control temperature, humidity, pressure, flow and PH.**

series controllers are microprocessor based controllers. Which have been designed with high accuracy input, various output selection, useful options and good reliability at a competitive price.

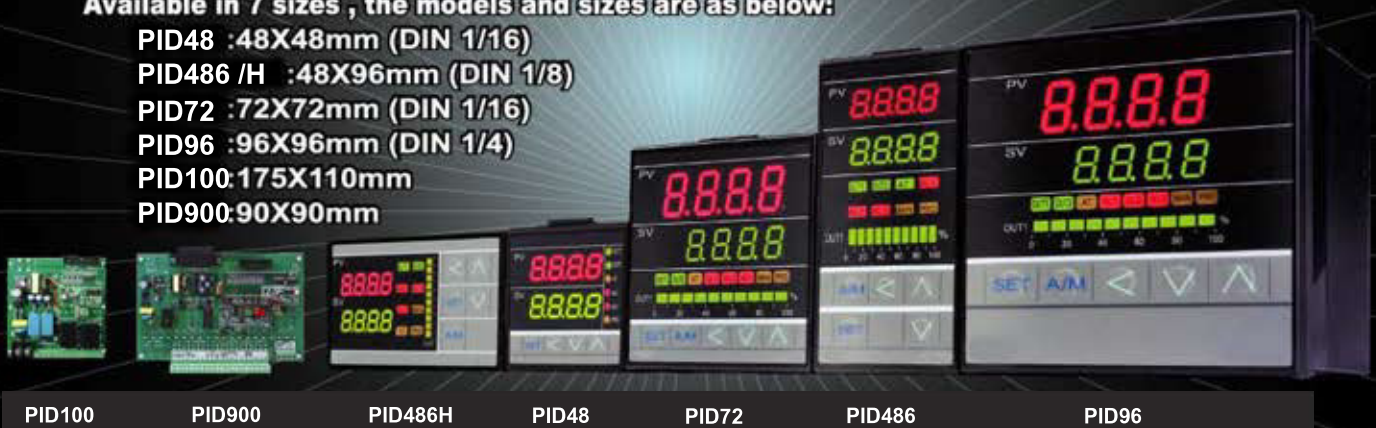
series use "PID+FUZZY" algorithm to implement excellent control. The output status is displayed on the built in "Bar-Graph" display.



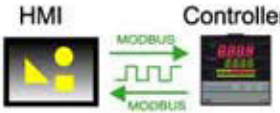
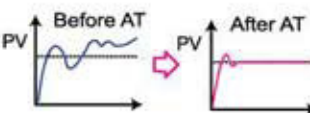



series not only provide the basic control output selections but also plus advanced options such as "Motor Valve Control", "SCR/TRIAC Trigger", and "Programmable RAMP/SOAK".

series support MODBUS protocol. Communication with HMI is more convenient. New additional HBA function with competitive price, user can upgrade system safety easy.

Available in 7 sizes, the models and sizes are as below:

- PID48 :48X48mm (DIN 1/16)
- PID486 /H :48X96mm (DIN 1/8)
- PID72 :72X72mm (DIN 1/16)
- PID96 :96X96mm (DIN 1/4)
- PID100:175X110mm
- PID900:90X90mm



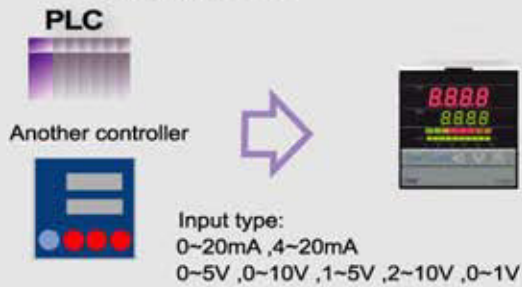
<p><b>CE Approval &amp; free power</b></p>	<p><b>IP65 Proof</b></p>
<p>All models get CE approval. Operate on any voltage from AC 85~265V at 50/60Hz. DC 24V is also available(optional function).</p>	<p> IP65 dust &amp; water proof is available for all models(optional function).</p>
<p><b>Heater Break Alarm (HBA)</b></p> <p> (Heater Break Alarm) Heater current flowing through CT can be displayed on controller. If heater current is less than HBA set value,AL1 will be activated (optional function).</p>	<p><b>MODBUS Communication</b></p> <p> HMI Controller PID series suport both MODBUS RTU and MODBUS ASCII protocol. Communication between controller and HMI or other equipment is more convenient(optional function).</p>
<p><b>Autotuning (AT)</b></p> <p> Before AT After AT AT Function can calculate the optimize PID value for your control system,without trying and error manually.</p>	<p><b>Auto/Manual mode</b></p> <p> Click! Conveniently switched between auto/manual output mode by clicking "A/M" key(except " PID48 ").</p>
<p><b>Various Indication Lamps</b></p> <p> Real time monitor the status of output(OUT1/OUT2),AT,alarm (AL1/AL2/AL3),manual output (MAN) and program(PRO).</p>	<p><b>Bar-Graph</b></p> <p> Ouput percent displayed on the bar-graph in 10 LEDs resolution(except " PID48 ").</p>
<p><b>High Accuracy</b></p> <p>Input with 14bit A/D resolution,0.2% accuracy of FS. Built in "AutoZero-AutoSpan" function keep good accuracy.</p>	<p><b>Data Lock Function</b></p> <p>All parameters are seperated in 3 operation levels. Each parameter can be hidden or locked to prevent unauthorized changes.</p>

## Various I/O Types

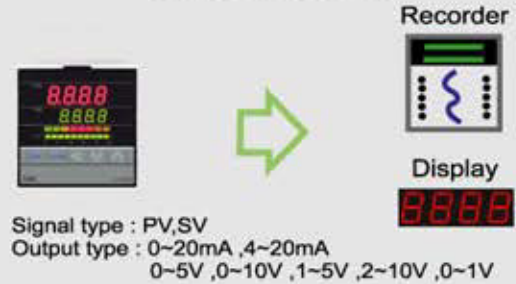


## Peripheral Options

### Remote SV

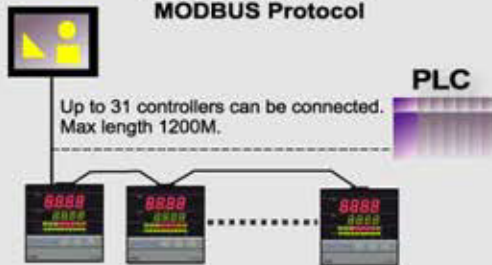


### Transmission



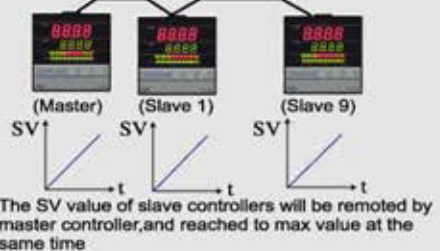
### Communication

(RS485 Communication)  
MODBUS Protocol



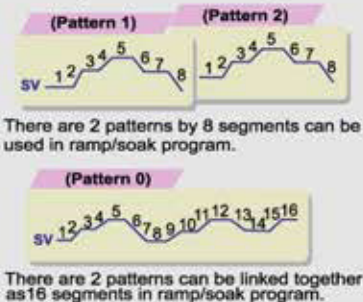
### Communication

(TTL Communication)  
Up to 10 controllers can be connected.  
Max length 1M.

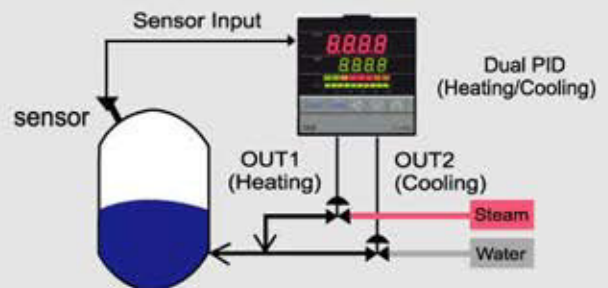


## Special Application

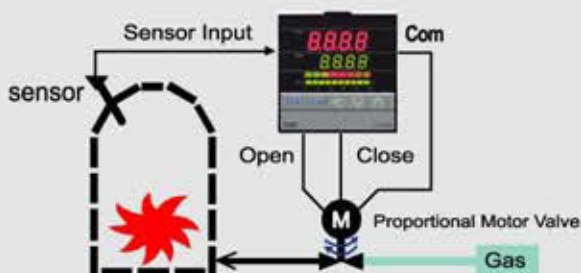
### Ramp/Soak Program



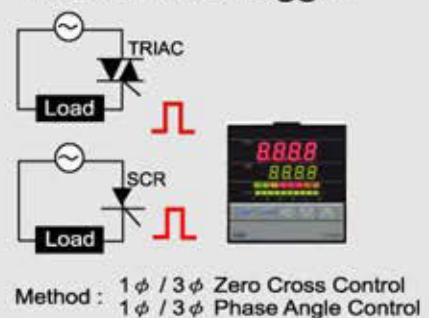
### Heating and Cooling Control



### Motor Valve Control

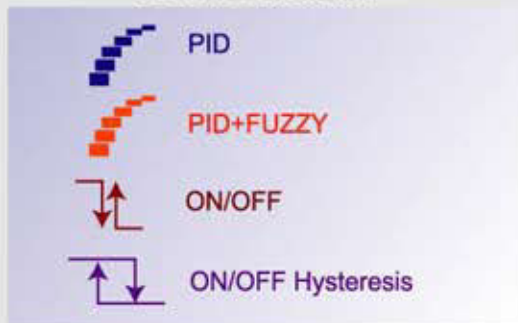


### SCR/TRIAC Trigger

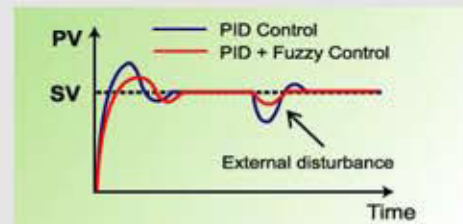


## Excellent Control

### Control Method

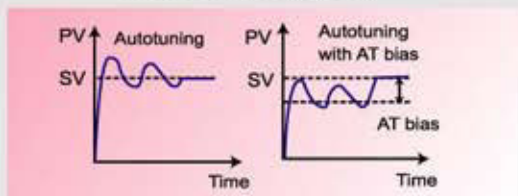


### Fuzzy Logic



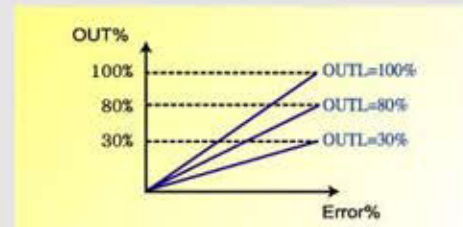
Built in fuzzy logic suppress the overshoot due to SV changes or external disturbance.

### Autotuning (AT)



When autotuning acts, it will make PV hunting 1~2 cycle to calculate optimize PID value. To protect user's device, FY series controller can perform PV hunting below SV by setting AT bias value(ATVL).

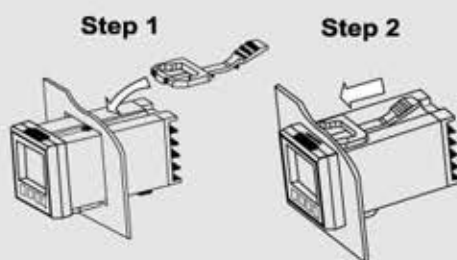
### Limit Setting



Built in output limit function. Use this function to get different gradient output and set limit for output.

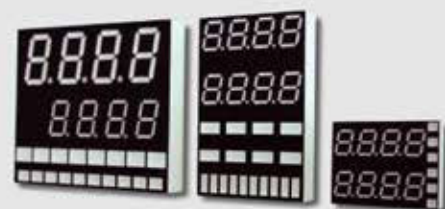
## Convenient Installation

### Easy Mounting



Just push the mounting bracket to panel. Without using any screws.

### New Display Module



New display module design more clear display and easy to read

## Alarm Function

### Alarm Types

Maximum with 3 sets of alarm.

Alarm types list as below:

#### Deviation

Deviation High Alarm  
Deviation Low Alarm  
Deviation High/Low Alarm  
Band Alarm

#### System

System Failed Alarm  
System Normal Alarm

#### PV

PV High Alarm  
PV Low Alarm

#### Program

Program Run Alarm  
Program End Alarm  
Segment End Alarm

### Delay Time

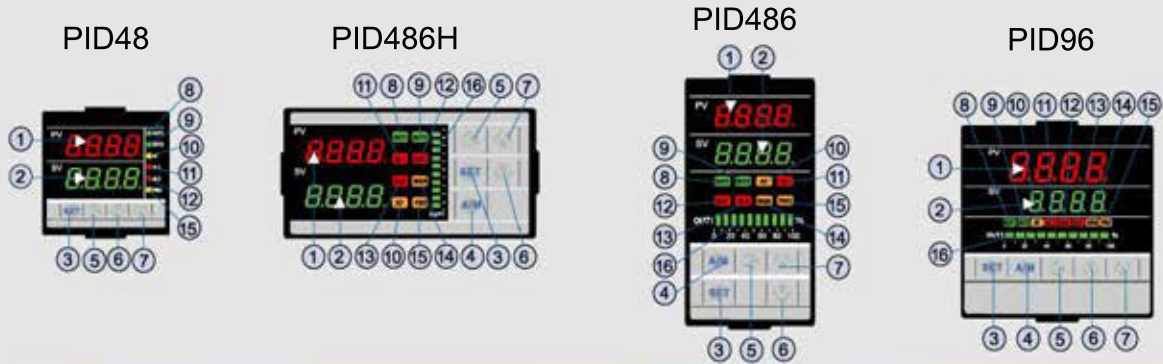
Use this function can avoid alarm acts frequently or acts due to external disturbance.



### Hold Function

Use this function can avoid alarm acts at start-up. The alarm action is suppressed at start-up until PV enters the non-alarm range.

## Parts Description



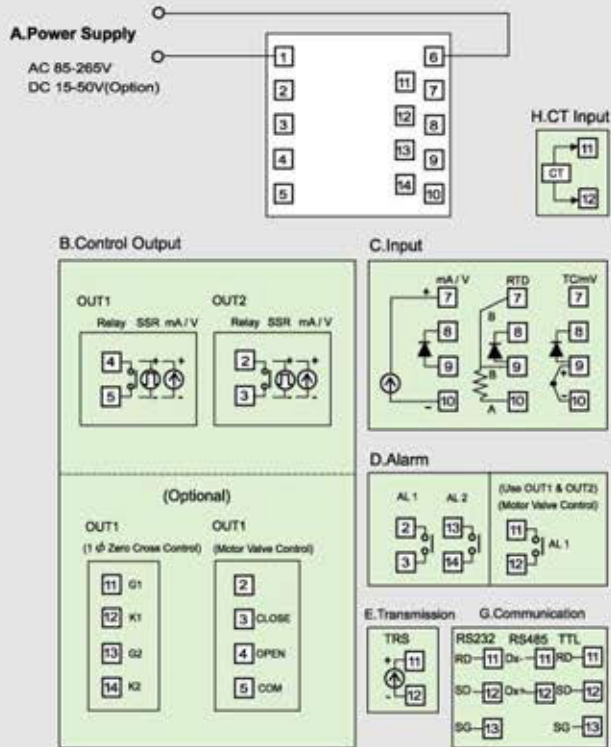
SYMBOL	NAME	FUNCTION	SYMBOL	NAME	FUNCTION
PV ①	Measured value (PV)display	Displays PV or various parameter symbols(Red)	OUT1 ⑧	OUT1 lamp	Lights when OUT 1 is on(Green)
SV ②	Setting value (SV)display	Displays SV or various parameter values(Green)	OUT2 ⑨	OUT2 lamp	Lights when OUT 2 is on(Green)
SET ③	Set Key	Used for parameter calling up and set value registration	AT ⑩	Autotuning lamp	Lights when Autotuning is activated(Orange)
A/M ④	Auto/Manual key	Switches between Auto(PID) output mode and Manual output	AL1 ⑪	Alarm 1 lamp	Lights when Alarm 1 is activated(Red)
< ⑤	Shift Key	Shift digits when settings are changed	AL2 ⑫	Alarm 2 lamp	Lights when Alarm 2 is activated(Red)
∨ ⑥	Down Key	Decrease numbers (*Only for programmable controller)	AL3 ⑬	Alarm 3 lamp	Lights when Alarm 3 is activated(Red)
∧ ⑦	Up Key (*Program Run)	Increase numbers (*Only for programmable controller)	MAN ⑭	Manual output lamp	Lights when manual output is activated (Orange)
			PRO ⑮	Program Running lamp	Flashes when program running (Only for programmable controller)
			OUT% ⑯	Output % Bar-Graph display	Output % is displayed on 10-dot LEDs

## External Dimension

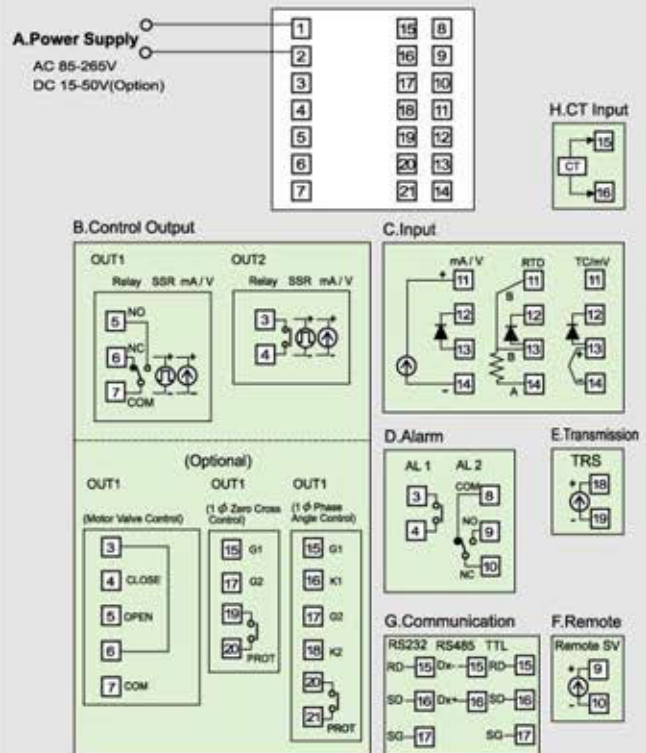
Unit : mm

PID48			
PID486H			
PID72			
PID486			
PID96			
PID100			

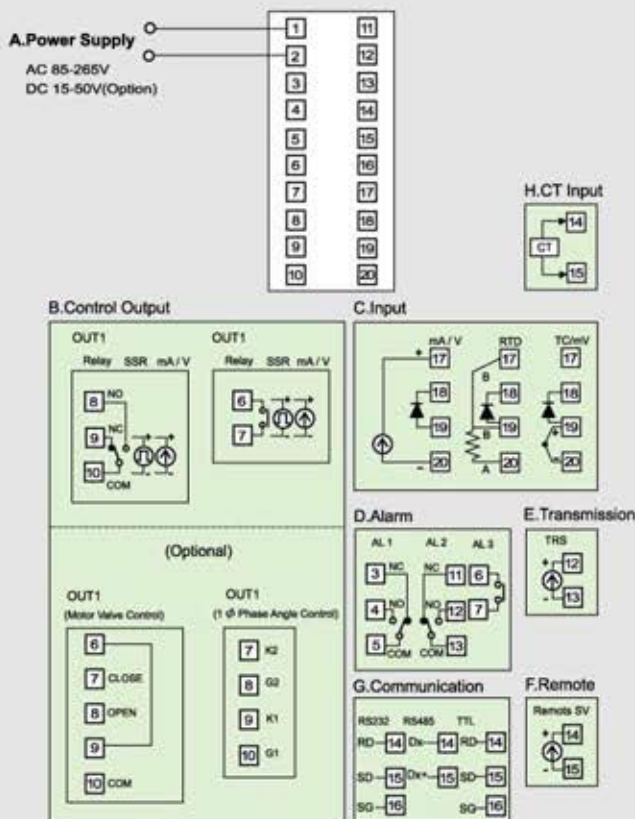
## PID48



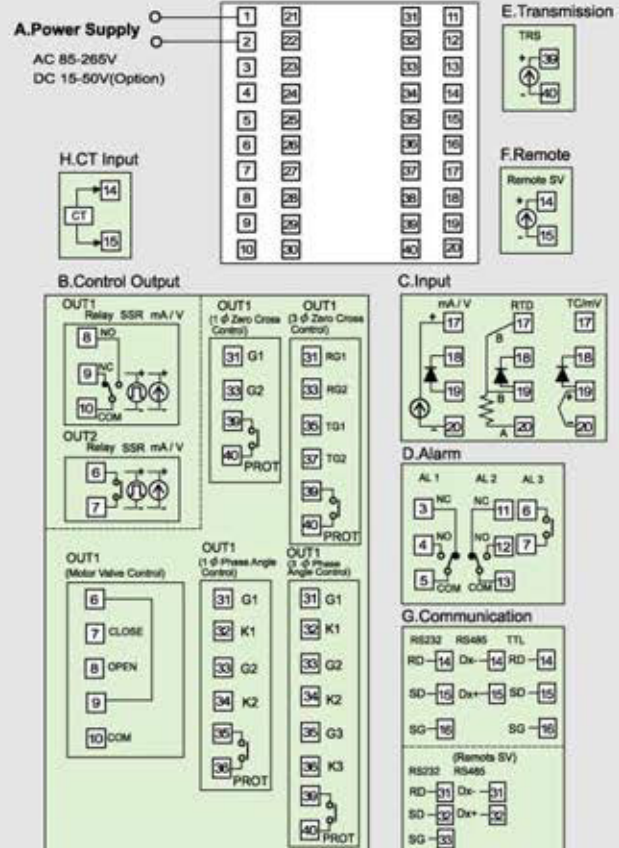
## PID72



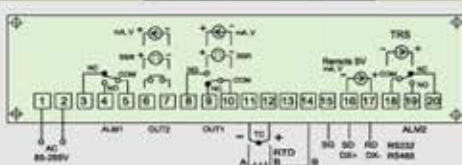
## PID486/486H



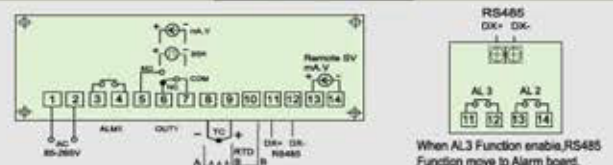
## PID96



## PID100



## PID900



## Standard Spec.

Model	PID48	PID486H	PID72	PID486	PID96	PID900	PID100
Dimension	48X48mm	96X48mm	72X72mm	48X96mm	96X96mm	175X110mm	90X90mm
Supply voltage	AC 85~265V , DC24V (Optional)					AC 85~265V	
Frequency	50/60 HZ						
Power Consumption	approx 3VA	approx 4VA	approx 3VA	approx 4VA	approx 4VA	approx 4VA	approx 3VA
Memory	Non-volatile memory E <sup>2</sup> PROM						
Input	Accuracy : 0.2%FS, Sample time : 250ms						
TC	K , J , R , S , B , E , N , T , W5Re/W26Re , PL2 , U , L						
RTD	DPT100 , JPT100 , JPT50						
mA dc	4~20mA , 0~20mA						
Voltage dc	0~1V , 0~5V , 0~10V , 1~5V , 2~10V -10~10mV , 0~10mV , 0~20mV , 0~50mV , 10~50mV						
DP Position	0000 , 000.0 , 00.00 , 0.000 (available for mA or Voltage dc input)						
Output 1	Main control output						
Relay	SPST type	SPDT type	SPDT type	SPDT type	SPDT type	SPDT type	SPDT type
	3A , 220V , electrical life : 100,000 times or more(under the rated load).						
Voltage Pulse	For SSR drive. ON:24V , OFF:0V , maximum load current:20mA.						
mA dc	4~20mA , 0~20mA .Maximum load resistance:560 Ω						
Voltage dc	0~5V , 0~10V , 1~5V , 2~10V. Maximum load current:20mA.						
Alarm 1	SPST type	SPDT type	SPST type	SPDT type	SPDT type	SPDT type	SPST type
	3A , 220V , electrical life : 100,000 times or more(under the rated load).						
Control algorithms	PID , P , PI , PD , ON/OFF(P=0) , FUZZY						
PID range	P:0~200% , I:0~3600 Secs , D:0~900 Secs						
Isolation	Output terminal (control output , alarm ,transmission) and Input terminal are isolated separately.						
Isolated resistance	10M Ω or more between input terminals and case(ground) at DC 500V 10M Ω or more between output terminals and case(ground) at DC 500V						
Dielectric strength	1000V AC for 1 minute between input terminals and case(ground) 1500V AC for 1 minute between output terminals and case(ground)						
Operating temperature	0~50° C						
Humidity range	20~90% RH						
Weight (approx)	approx 150g	approx 225g	approx 225g	approx 225g	approx 300g	approx 130g	approx 80g
Display Height	PV:7mm SV:7mm	PV:7mm SV:7mm	PV:14mm SV:10mm	PV:7mm SV:7mm	PV:14mm SV:10mm	External Interface Unit.	External Interface Unit.

## Optional Spec.

Model	FY400	FY600	FY700	FY800	FY900	FY100	FY101
RAMP/SOAK Program	2 Patterns with 8 segments each . The 2 patterns can be linked together as 16 segments use						
Output 2	For heating and cooling control use						
Relay	SPST type	SPST type	SPST type	SPST type	SPST type	SPST type	SPST type
Voltage Pulse	For SSR drive. ON:24V , OFF:0V , maximum load current:20mA.						
mA dc	4~20mA , 0~20mA .Maximum load resistance:560 Ω						
Voltage dc	0~5V , 0~10V , 1~5V , 2~10V. Maximum load current:20mA.						
Alarm 2	SPST type	SPDT type	SPDT type	SPDT type	SPDT type	SPDT type	SPST type
Alarm 3	None	SPST type	SPST type	SPST type	SPST type	SPST type	SPST type
Heater Break Alarm (HBA)	Display Range of Heater Current:0.0~99.9A , Accuracy : 1%FS Included CT :SC_80_T (5.8mm dia , 0.0~80.0A) or SC_100_T(12mm dia , 0.0~99.9A) Alarm Relay : AL1						
Transmission	Available for PV or SV transmission						
mA dc	4~20mA , 0~20mA. Maximum load resistance : 560 Ω						
Voltage dc	0~5V,0~10V,1~5V,2~10V. Maximum load current : 20mA.						
Remote SV Input	4~20mA , 0~20mA , 0~5V , 0~10V , 1~5V , 2~10V are available						
Communication	Protocol : MODBUS RTU,MODBUS ASCII Interface : RS232 , RS485 , TTL Baudrate : 38400 , 19200 , 9600 , 4800 , 2400 bps. 8 bit , Start bit : 1 bit , Parity : Odd or Even , Stop bit : 1 or 2 bit						
WaterProof/DustProof	IP65					None	None

## Model & Suffix codes

Model	Output1	Output2	Alarm	TRS	Remote SV	Commu- nication	Input Type	Power	Water/Dust Proof
<b>PID48</b>	<b>1</b>	<b>0</b>	<b>1</b>	<b>0</b>	<b>0</b>	<b>0</b>	<b>02</b>	<b>A</b>	<b>N</b>
PID48	48x48mm	0 None	0 None	0 None	0 None	0 None	See Input Codes	A AC 85~265V	N None
PID486H	96x48mm	1 Relay	1 Relay	1 1 Set	1 4~20mA	1 4~20mA		D DC 24V	W IP65
PID72	72x72mm	2 Voltage Pulse (SSR Drive)	2 Voltage Pulse (SSR Drive)	2 2 Sets	2 0~20mA	2 0~20mA	B Board Type AC85~265V pluggable terminal block		
PID486	48x96mm	3 4~20mA	3 4~20mA	3 3 Sets	A 0~5V	A 0~5V		A RS232_MODBUS	
PID96	96x96mm	4 0~20mA	4 0~20mA	A HBA*	B 0~10V	B 0~10V	B RS485_MODBUS		
Board Type		A 0~5V	A 0~5V	B HBA+AL2	C 1~5V	C 1~5V			
PID100	175x110mm	B 0~10V	B 0~10V	C HBA+AL2+AL3	D 2~10V	D 2~10V			
PID900 (STANDARD)	90x90mm	C 1~5V	C 1~5V						
PPID48	48x48mm	D 2~10V	D 2~10V						
PPID486H	96x48mm	5 1 φ SCR zero cross control							
PPID72	72x72mm	6 3 φ SCR zero cross control							
PPID486	48x96mm	7 Motor valve control							
PPID96	96x96mm	8 1 φ SCR phase angle control							
Board Type		9 3 φ SCR phase angle control							
PID100	175x110mm								
PID900 (RAMP/SOAK Programmable)	90x90mm								

\* : Block means optional functions with additional charge

\* HBA : Heater Break Alarm(HBA must use AL1 as alarm relay)

## Combination of options and models

Options	RAMP/SOAK PROGRAM	Output 1			Output2	Alarm2	Alarm3	HBA	Transmission	Remote SV	Communication	DC 24V Power
Model		1 φ SCR_Z	3 φ SCR_Z	Motor valve control	1 φ SCR_P	3 φ SCR_P						
PID48	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
PID486	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
PID72	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
PID486H	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
PID96	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
PID100	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
PID900	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>

Available  Not available

\* Remote SV function is not available, if HBA Function has been specified.

## Input type table

Type	Code	Range	Type	Code	Range	Type	Code	Range	
TC	K	K1 01	0.0~200.0°C(392.0°F)	K2 02	0.0~400.0°C(752.0°F)	K3 03	0~600°C(1112°F)	LINEAR	
		K4 04	0~800°C(1472°F)	K5 05	0~1000°C(1832°F)	K6 06	0~1200°C(2192°F)		
	J	J1 07	0.0~200.0°C(392.0°F)	J2 08	0.0~400.0°C(752.0°F)	J3 09	0~600°C(1112°F)		
		J4 10	0~800°C(1472°F)	J5 11	0~1000°C(1832°F)	J6 12	0~1200°C(2192°F)		
	R	R1 13	0~1600°C(2912°F)	R2 14	0~1769°C(3216°F)				
	S	S1 15	0~1600°C(2912°F)	S2 16	0~1769°C(3216°F)				
	B	B1 17	0~1820°C(3308°F)						
	E	E1 18	0~800°C(1472°F)	E2 19	0~900°C(1652°F)				
	N	N1 20	0~1200°C(2192°F)	N2 21	0~1300°C(2372°F)				
	T	T1 22	-199.9~400.0°C(752.0°F)	T2 23	-199.9~200.0°C(392.0°F)	T3 24	0.0~350.0°C(662.0°F)		
W	W1 25	0~2000°C(3632°F)	W2 26	0~2320°C(4208°F)					
PLI	PL1 27	0~1300°C(2372°F)	PL2 28	0~1390°C(2534°F)					
U	U1 29	-199.9~600.0°C(999.9°F)	U2 30	-199.9~200.0°C(392.0°F)	U3 31	0.0~400.0°C(752.0°F)			
L	L1 32	0~400°C(752°F)	L2 33	0~800°C(1472°F)					
RTD	JPT	JP1 41	-199.9~600.0°C(999.9°F)	JP2 42	-199.9~400.0°C(752.0°F)	JP3 43	-199.9~200.0°C(392.0°F)	AN1 61	-10~10mV
	100	JP4 44	0~200°C(392°F)	JP5 45	0~400°C(752°F)	JP6 46	0~600°C(1112°F)	62	-2~2V
	PT	DP1 47	-199.9~600.0°C(999.9°F)	DP2 48	-199.9~400.0°C(752.0°F)	DP3 49	-199.9~200.0°C(392.0°F)	63	-5~5V
	100	DP4 50	0~200°C(392°F)	DP5 51	0~400°C(752°F)	DP6 52	0~600°C(1112°F)	64	-10~10V
	JPT	JP1 53	-199.9~600.0°C(999.9°F)	JP2 54	-199.9~400.0°C(752.0°F)	JP3 55	-199.9~200.0°C(392.0°F)	AN2 71	0~10mV
	50	JP4 56	0~200°C(392°F)	JP5 57	0~400°C(752°F)	JP6 58	0~600°C(1112°F)	AN3 76	0~20mV
								AN4 81	0~50mV
								82	0~20mA
							83	0~1V	
							84	0~5V	
							85	0~10V	
							86	0~5K ohm	
							87	0~2V	
							AN5 91	10~50mV	
							92	4~20mA	
							93	1~5V	
							94	2~10V	

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